Leo Torres and Tina Eliassi-Rad Northeastern University

The scientific, computational, and mathematical study of real-life systems that can be represented as graphs.

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offline social networks



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offline social networks online social networks



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Spectral graph theory. Eigenvector centrality. PageRank.



Modern topics:

- graph signals
- graph symmetries
- generalizations
 - of graphs: simplicial complexes, hypergraphs
 - of matrices: tensors
- applications: synchronization, cybersecurity, epidemiology, etc
- "other" matrices e.g. non-backtracking matrix

Perturbation of Non-Backtracking Eigenvalues: Centrality and Diagonalizability

Leo Torres with Kevin S. Chan, Hanghang Tong, Tina Eliassi-Rad







Non-backtracking Matrix





G = (V, E)|E| = m

B

Non-backtracking eigenvalues

- length spectrum theory
 - o Torres, et al. App. Net. Sci. 4.1 (2019): 41.
- community detection
 - Krzakala, et al. PNAS 110.52 (2013): 20935-20940.
 - Bordenave, et al. FOCS (2015).
- graph distance & embedding
 - Torres, et al. App. Net. Sci. 4.1 (2019): 41.
- centrality
 - Martin, et al. Phys. Rev. E 90.5 (2014): 052808.
 - Morone & Makse. Nature 524.7563 (2015): 65-68.
 - Arrigo, et al. J. of Sci. Comp. 80.3 (2019): 1419-1437.

• epidemic thresholds (SIR, SIS)

- Karrer, et al. Phys. Rev. Lett. 113.20 (2014): 208702.
- Hamilton, & Pryadko. Phys. Rev. Lett. 113.20 (2014): 208701.
- Shrestha, et al. Phys. Rev. E 92.2 (2015): 022821.
- Castellano, & Pastor-Satorras. Phys. Rev. E 98.5 (2018): 052313.
- Masuda, et al. J. of App. Math. 85.2 (2020): 214-230.



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L. Torres, et al.

Nonbacktracking Eigenvalues under Node Removal: X-Centrality and Targeted Immunization.

SIMODS, 3(2). 2021.





Block Matrix





Block Matrix





Block Matrix





The X Matrix





$$\det\left(B^c - tI\right) = 0$$



 $\det\left(B^c-tI\right)=0$

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X = DFE

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 $\bullet \quad \bullet \quad \bullet$

$$t^2(t-\lambda_1)+v_1^TXu_1=0$$



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$$t^2(t-\lambda_1)+\overbrace{v_1^TXu_1}=0$$

 u_1, v_1 = right and left eigenvectors

XNB Centrality



• • • X-non-backtracking centrality

$$\lambda_1)+\overbrace{v_1^TXu_1}=0$$

 $u_1, v_1 =$ right and left eigenvectors

It decreases by a quantity that is correlated to $v_1^T X u_1$

XNB and the true change in eigenvalue



XNB and the true change in eigenvalue





• Many ways of deriving this...

 $t^2(t-\lambda_1)+v_1^TXu_1=0$

- Many ways of deriving this...
- The cleanest way assumes the matrix is diagonalizable.

$$t^2(t-\lambda_1)+v_1^TXu_1=0$$

- Many ways of deriving this...
- The cleanest way assumes the matrix is diagonalizable.
- When is the non-backtracking matrix diagonalizable?

$$t^2(t-\lambda_1)+v_1^TXu_1=0$$

• When is the non-backtracking matrix diagonalizable?

L. Torres

Non-backtracking Spectrum: Unitary Eigenvalues and Diagonalizability.

arXiv preprint arXiv:2007.13611 (2020).

- When is the non-backtracking matrix diagonalizable?
 - What is the multiplicity of the eigenvalues with unit magnitude?

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G









 m_H

Cubic roots of unity



$m_G + 1 \equiv m_H$



Subdivisions

S



Subdivisions S_2 S

Subdivisions S_r S-rr r Ň r

Arbitrary subdivisions

G



 S_r

H



Arbitrary subdivisions

G







H

 $m_G + m_{S_r} \equiv m_H$



 $m_G + m_{S_r} \equiv m_H$



Theorem. Gluing a graph subdivision is the only way that unitary eigenvalues appear in the spectrum.



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www.leotrs.com leo@leotrs.com @_leotrs